

Heavy Industrial • J1939 CANbus

Linear Position/Velocity to 550 inches (1400 cm) **Aluminum or Stainless Steel Enclosure Options VLS Option To Prevent Free-Release Damage IP67 • NEMA 6 Protection**



Full Stroke Range Options	(on this datasheet)	0-75 to 0-550 inches			
Electrical Signal Interface		CANbus SAE J1939			
Protocol		Proprietary B			
Accuracy		± 0.10% full stroke			
Repeatability		± 0.02% full stroke			
Resolution		± 0.003% full stroke			
Measuring Cable Options	nylon-coated stair	nless steel or thermoplastic			
Enclosure Material	powder-painted a	aluminum or stainless steel			
Sensor	plastic-hybr	id precision potentiometer			
Potentiometer Cycle Life		≥ 250,000 cycles			
Maximum Retraction Acce	see ordering information				
Maximum Velocity		see ordering information			
Weight, Aluminum (Stainle	ss Steel) Enclosure	8 lbs. (16 lbs.), max.			

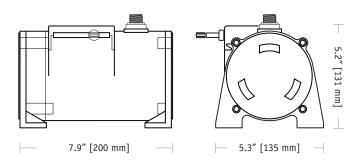
ELECTRICAL

Input Voltage	7 - 18 VDC
Input Current	60 mA max.
Address Setting/Node ID	063 set via DIP switches
Baud Rate	125K, 250K or 500K set via DIP switches
Update Rate	10 ms. (20 ms. available, contact factory)

ENVIRONMENTAL

Enclosure	NEMA 4/4X/6, IP 67
Operating Temperature	-40° to 200°F (-40° to 90°C)
Vibration	up to 10 g to 2000 Hz maximum

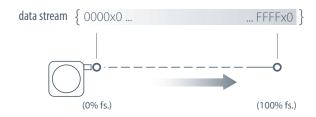




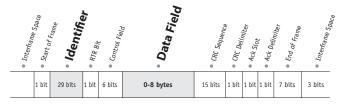
The PT9CN communicates linear position feedback via the CANbus SAE J1939 interface. The PT9CN has been designed for factory and harsh environment applications requiring full stroke ranges up to 550".

As a member of Celesco's innovative family of NEMA 4 rated cable-extension transducers, the PT9CN installs in minutes by simply mounting it's body to a fixed surface and attaching it's cable to the movable object. Perfect parallel alignment not required.

Output Signal:



I/O Format and Settings



repetition = 8 msec.

Identifier

ier –	Mess	age Pr	iority	Fut U:	ure				939 R Propri							Da	ta Fie	eld Ty	pe*			Not	Used		N	lode 1	D**		
Example –	1	0	0	0	0	1	1	1	1	1	1	1	1	0	1	0	1	0	0	1	1	0	0	1	1	1	1	1	1
Identifier Bit No. –	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Hex Value –			()			ı	F			ı	F				5			3	3			3	3			-	=	

*Sensor field data can be factory set to customer specific value. **Customer defined, set via Dips 1-6. Bit values shown for example only, see Address Setting below.

Data Field

 $\mathbf{B_0} = \mathsf{LSB}$ current % of measurement range byte $\mathbf{B_1} = \mathsf{MSB}$ current % of measurement range byte

B₂ = LSB current measurement count byte

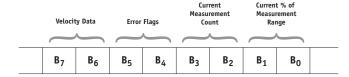
B₃ = MSB current measurement count byte

B₄ = error flag

B₅ = error flag

B₆ = LSB velocity data byte

B7 = MSB velocity data byte





Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable. The CMC is a 16-bit value that occupies bytes B_2 and B_3 of the data field. B_2 is the LSB (least significant byte) and B_3 is the MSB (most significant byte).

The **CMC** starts at **0x0000** with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at **0xFFFF**. This holds true for all ranges.

Converting CMC to Linear Measurement

To convert the current measurment count to inches or millimeters, simply divide the count by 65,535 (total counts over the range) and then multiply that value by the full stroke range:

$$\left(\frac{\text{current measurement}}{\text{count}}\right) \times \text{full stroke} \\ \frac{65535}{\text{range}}$$

Sample Conversion:

If the full stroke range is **30 inches** and the current position is **0x0FF2** (4082 Decimal) then,

$$\left(\frac{4082}{65.535}\right)$$
 X 30.00 inches = 1.87 inches

If the full stroke range is **625 mm** and the current position is **0x0FF2** (4082 Decimal) then,

$$\left(\frac{4082}{65,535}\right)$$
 X 625 mm = 39 mm

B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Current % of Measurement Range

The Current % of Measurement Range is a 2-byte value that expresses the current linear position as a percentage of the entire full stroke range. Resolution is .1 % of the full stroke measurement range.

This value starts at **0x0000** at the beginning of the stroke and ends at **0x03E8**.

Example:

Hex	Decimal	Percent
0000	0000	0.0%
0001	0001	0.1%
0002	0002	0.2%
•••	•••	•••
03E8	1000	100.0%



Error Flags

0x55 (yellow LED on controller board) indicates that the sensor has begun to travel beyond the calibrated range of the internal position potentiometer.

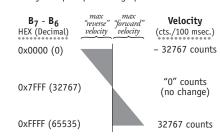
OxAA (red LED on controller board) indicates that the sensor has moved well beyond the calibrated range of the internal position potentiometer.

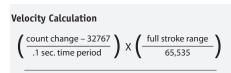
If either error flag occurs within the full stroke range of the sensor, the unit should be returned to the factory for repair and recalibration.

B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Velocity

Data in bytes ${\bf B_7}$ - ${\bf B_6}$ is the change in the CMC (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.





Sample Calculations

Cable Extension (positive direction):

 $B_7 - B_6 = 0 \times 8006$ (32966 Dec), full stroke = 200 in.

$$\left(\frac{32966 - 32767}{.1 \text{ sec}}\right) X \left(\frac{200 \text{ in.}}{65,535}\right) = 6.07 \text{ in.} / \text{sec.}$$

Cable Retraction (negative direction):

 $B_7 - B_6 = 0x7F1A$ (32538 Dec), full stroke = 200 in.

$$\left(\frac{32538 - 32767}{.1 \text{ sec}}\right) \chi \left(\frac{200 \text{ in.}}{65,535}\right) = -6.99 \text{ in. / sec.}$$



Setting the Address (Node ID) and Baud Rate

Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number $1 (= 2^0)$ and ending with switch number $6 (= 2^5)$.

Baud Rate

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

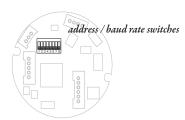
The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

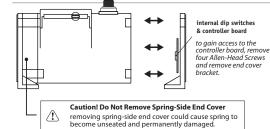
DIP-8

0

DTP-7

CANBus Controller Board





DIP-1 (2 ⁰)	DIP-2 (2 ¹)	DIP-3 (2 ²)	DIP-4 (2 ³)	DIP-5 (2 ⁴)	DIP-6 (2 ⁵)	address (decimal)
0	0	0	0	0	0	0
1	0	0	0	0	0	1
0	1	0	0	0	0	2
•••		•••				
1	1	1	1	1	1	63

0	1	500k
1	1	125k

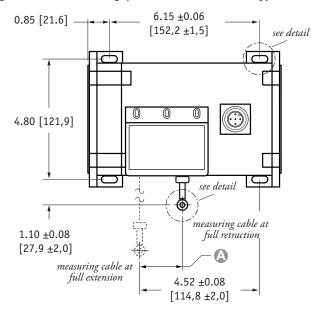
12345678 **v** ="1"

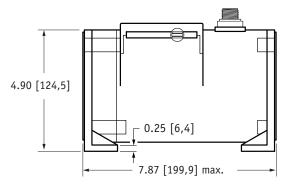
baud rate

125k

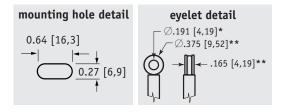
250k

Fig. 1 – Outline Drawing (18 oz. cable tension only)





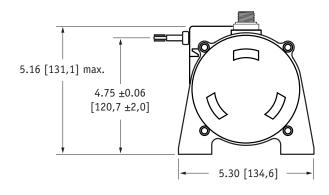
DIMENSIONS ARE IN INCHES [MM] tolerances are 0.03 IN. [0.5 MM] unless otherwise noted.



A DIMENSION (INCHES)

MEASURING CABLE

RANGE	Ø .031 in.	Ø . 034 in.	Ø .047 in.	in. Ø.062 in.			
75	n/a	0.22	0.29	0.37			
100	n/a	0.29	0.39	0.49			
150	n/a	0.44	0.59	0.73			
200	n/a	0.58	0.79	0.98			
250	n/a	0.73	0.98	1.22			
300	n/a	0.88	1.18	1.47			
350	n/a	1.02	1.38	1.71			
400	n/a	1.17	1.57	1.96			
450	n/a	1.31	1.77	n/a			
500	n/a	1.46	1.97	n/a			
550	1.61	1.61	n/a	n/a			



^{*} tolerance = +.005 -.001 [+.13 -.03]

^{**} tolerance = +.005 -.005 [+.13 -.13]

Ordering Information:

Model Number:

Sample Model Number:

PT9CN - 200 - AL - N34 - 26 - FR - J - 500 - 32 - SC5

200 inches aluminum .034 nylon-coated stainless

ange:
ange:
neasuring cable:
measuring cable tension:
cable exit:
interface:
baud rate:
node ID:
electrical connection: 18 oz. front (horizontal) CANbus SAE J1939 500 k bits/sec.

32 decimal 5-meter cordset with straight plug

Full Stroke Ranae:

R <u>order code:</u>	75	100	150	200	250	300	350	400	450*	500*	550*
full stroke range, min:	75 in.	100 in.	150 in.	200 in.	250 in.	300 in.	350 in.	400 in.	450 in.	500 in.	550 in.

* – 36 oz. cable tension strongly recommended

Enclosure Material:

♠ order code: SS powder-painted aluminum 303 stainless

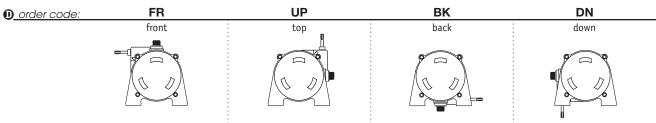
Measuring Cable:

B order code:	N34	S47	S31	V62
cable construction:	Ø.034-inch nylon-coated stainless steel rope	Ø.047-inch bare stainless steel rope	Ø.031-inch bare stainless steel rope	Ø.058-inch PVC jacketed vectra fiber rope
available ranges:	all ranges	all ranges up to 500 inches	550 inch range only	all ranges up to 400 inches
general use:	indoor	outdoor, debris, high temperature	outdoor, debris, high temperature	high voltage or magnetic field

Measuring Cable Tension:

6 order code:		26	52	
tension (30%):	1	8 oz.	36 oz.	
enclosure material:	aluminum	stainless steel	aluminum stainless steel	
max. acceleration:	1 g	.33 g	5 g 2 g	
max. velocity:	60 inches/sec	20 inches/sec	200 inches/sec 80 inches/sec	
		standard housing see fig 1.	dual-spring housing see fig 2.	

Cable Exit:



Baud Rate:

125 250 500 **B** order code: 125 kbaud 250 kbaud 500 kbaud



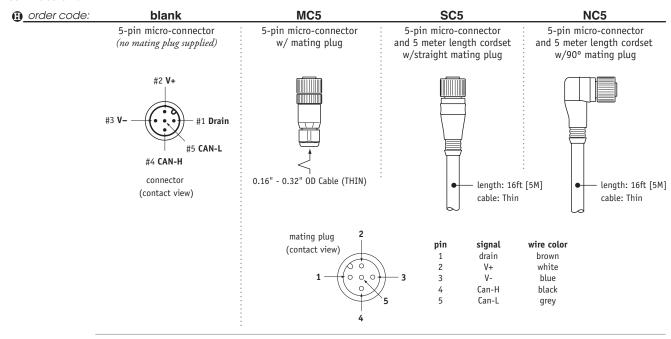
Ordering Information (cont.):

Node ID:

0 61 62 63 **6** order code

select address (0 - 63 Decimal)

Electrical Connection:



VLS Option - Free Release Protection

The patented Celesco Velocity Limiting System (VLS) is an option for PT9000 Series cable extension transducers that limits cable retraction to a safe 40 to 55 inches per second for the single spring option and 40 to 80 inches per second for the higher tension dual spring option.

The VLS option prevents the measuring cable from ever reaching a damaging velocity during an accidental free release. This option is ideal for mobile applications that require frequent cable disconnection and reconnection. It prevents expensive unscheduled downtime due to accidental cable mishandling or attachment failure.

How To Configure Model Number for VLS Option:



creating VLS model number (example)...

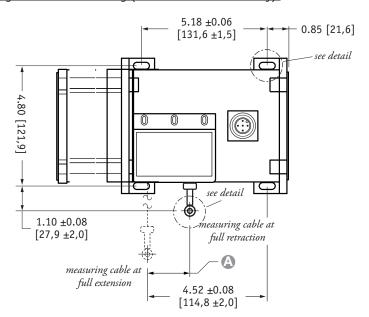
PT9CN-200-N34-26... 1. select PT9CN model

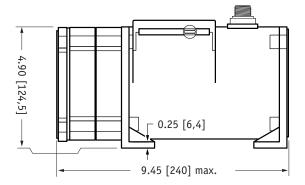
X79CN-200-N34-26... 2. remove "PT" from the model number

VLS + CN-200-N34-26... 3. add "VLS"

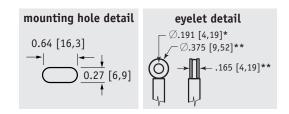
VLSCN-200-N34-26... 4. completed model number!

Fig. 2 – Outline Drawing (36 oz. cable tension only)





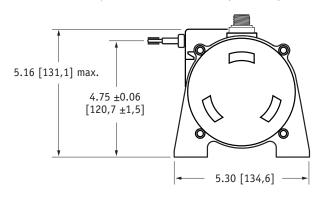
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A DIMENSION (INCHES)

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150	n/a	0.44	0.59	0.73
200	n/a	0.58	0.79	0.98
250	n/a	0.73	0.98	1.22
300	n/a	0.88	1.18	1.47
350	n/a	1.02	1.38	1.71
400	n/a	1.17	1.57	1.96
450	n/a	1.31	1.77	n/a
500	n/a	1.46	1.97	n/a
550	1.61	1.61	n/a	n/a



* tolerance = +.005 -.001 [+.13 -.03] ** tolerance = +.005 -.005 [+.13 -.13]

version: 11.0 last updated: June 24, 2014